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Mereotopology: A theory of parts and boundaries

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Abstract

The paper is a contribution to formal ontology. It seeks to use topological means in order to derive ontological laws pertaining to the boundaries and interiors of wholes, to relations of contact and connectedness, to the concepts of surface, point, neighbourhood, and so on. The basis of the theory is mereology, the formal theory of part and whole, a theory which is shown to have a number of advantages, for ontological purposes, over standard treatments of topology in set-theoretic terms. One central goal of the paper is to provide a rigorous formulation of Brentano's thesis to the effect that a boundary can exist as a matter of necessity only as part of a whole of higher dimension of which it is the boundary. It concludes with a brief survey of current applications of mereotopology in areas such as natural-language analysis, geographic information systems, machine vision, naive physics, and database and knowledge engineering.

Keywords: Topology; Mereology; Cognitive science; Formal ontology; Naive physics

1. Introduction

The term 'ontology' has recently acquired a certain currency within the knowledge-engineering community, especially in relation to the ARPA knowledge-sharing initiative [27,44]. The term is used in a number of different senses, however, not all of them clear or mutually compatible. Here I follow philosophical tradition in conceiving ontology as the science which deals with the nature and the organisation of reality. Ontology thus conceived may be formal, in the sense that it is directed towards formal structures and relations in reality. This formal ontology is contrasted with the various material ontologies (of physics, chemistry, medicine, and so on) which study the nature and organisation of specific sub-regions of reality. Formal structures, for example the structures governing the relation of part to whole, are shared in common by all material domains. Both formal and material ontologies may be pursued with the aid of the machinery of axiomatic theories, and it is axiomatic formal

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ontology that has proved to be of most interest for the ontology-building purposes of the knowledge engineer.

The term 'formal ontology' was introduced by Edmund Husserl in his *Logical Investigations* [39] (1st German edition 1900/01), and the mereology or formal theory of part and whole there developed by Husserl is still, of all the component disciplines of formal ontology, that which has received the most developed axiomatic treatment. Mereotopology, the subject of the present essay, is built up out of mereology together with a topological component, thereby allowing the formulation of ontological laws pertaining to the boundaries and interiors of wholes, to relations of contact and connectedness, to the concepts of surface, point, neighbourhood, and so on.

Our understanding of mereotopological principles rests on philosophical and logical studies both classical—here Aristotle, Brentano and Whitehead deserve special mention (see also [45,75])—and modern [1ff,5,10,16,17,19,62,69,70,78]. Too much of the artificial intelligence literature in the areas of formal ontology and naive physics has, however, not drawn from these sources, but has rather been dominated by the use of set-theoretical instruments not conducive to the direct representation of mereological and topological structures. The work of Cohn and his associates [13,25f,59ff], see also [4]) is an exception to this rule, and has done much to demonstrate the fruitfulness of the mereotopological alternative for knowledge-engineering purposes. This work is, however, based on the Whitehead-inspired system of Clarke [11,12] which is problematic for at least the following reasons:

1. The system has a single primitive, that of connection, in terms of which the notion of part is defined by means of what, intuitively, appears to be a logical trick. This means that the mereological and topological components of the resultant theories are difficult or impossible to separate formally. The power of the approach is thus reduced, since experiments in axiom-adjustment at different points in the theory cannot be carried out in controlled fashion. Moreover, there are associated formal difficulties with the system (discussed by Varzi in his paper in this volume) which contradict the goal of formal ontology as a realistic, descriptive enterprise.
2. The system rests on a no-longer-fashionable conception of formal ontology (embraced by Lesniewski and his followers, by Carnap, Goodman, and others) according to which the goal of minimizing the number of non-logical primitives (ideally to the point where a system would have precisely one such primitive) is taken to override other goals, such as the intuitive plausibility of definitions, easy testability of axioms, and so on. More recent experience in the construction of formal-ontological systems, for example for the purposes of naive physics [36], has suggested that systems capable of describing real-world phenomena will require large numbers of non-logical primitives, no group of which will be capable of being eliminated formally in favour of any other group.

The axiomatic version of what is here called 'basic mereotopology' is designed to serve as the starting point of a formal-ontological system which will be free of these defects. It rests on the two non-logical primitives of *part* (P) and *interior part* (IP), respectively. Connection (C) is then defined in terms of P and IP. Other versions of this basic theory have been proposed [66,77,78], [9] (Appendix), and a survey of the whole field is presented in [18], and in [81].

2. Constituency

Classical first-order logic with identity and descriptions will be assumed without ceremony. In a complete account we should have to employ the resources of a free logic, perhaps along the lines of [63], to take account of the fact that the term-forming operator ' σ ' introduced below is not defined for every predicate. Variables x , y , z , etc. will range over entities (particulars, individuals) in general. Here the term 'entity' is to be understood as ranging over *realia* of all sorts. Our quantifiers are otherwise unrestricted, embracing, inter alia, my left foot and the interstellar vacuum, my present headache and the 3-dimensionally extended colour of this green glass cube. They embrace what is continuous or discontinuous, bounded or unbounded, connected or non-connected, and they embrace also volumes of space and intervals of time, as well as 3-dimensional material things and their parts and moments.

We adopt as mereological primitive the relation of parthood or constituency. We say x is a **part** of y , and write ' $x P y$ ', when x is any sort of part of y , including an improper part (so $x P y$ will be consistent with x 's being identical to y). Three further purely mereological notions can be defined immediately:

$$\text{DP1 } x \text{ overlaps } y: \quad xOy: = \exists z(zPx \wedge zPy)$$

$$\text{DP2 } x \text{ is discrete from } y: \quad xDy: = \neg xOy$$

$$\text{DP3 } x \text{ is a point:} \quad Pt(x): = \forall y(yPx \rightarrow y = x)$$

As axioms governing P we shall assume the universal closures of:

$$\text{AP1 } xPy \equiv \forall z(zOx \rightarrow zOy)$$

$$\text{AP2 } xPy \wedge yPx. \rightarrow x = y$$

(Generally speaking we suppress all initial universal quantifiers in our statements of axioms and theorems.) From **AP1** and **AP2** and the usual axioms of identity it follows that our system of mereology is extensional ([62], Chapter 1), and, in particular, that $x = y \equiv \forall z(zPx \equiv zPy)$. From **AP1** it follows also that:

$$\text{TP1 } xPx \quad P \text{ is reflexive}$$

$$\text{TP2 } xPy \wedge yPz. \rightarrow xPz \quad P \text{ is transitive}$$

We say that a condition ' ϕ ' in a single free variable ' x ' is **satisfied** if and only if the sentence ' ϕx ' is true for at least one value of ' x '. Intuitively we are to suppose that each satisfied condition ' ϕ ' picks out a certain unique entity, the **sum** (fusion or join) of all those entities in the world which ϕ , an entity which we shall represent by ' $\sigma x(\phi x)$ '. Note that the sum of ϕ ers is to be distinguished from the extension of the concept ϕ : not everything that is in the sum of ϕ ers need itself be such as to ϕ (thus my leg is in the sum of Britons, but it is not itself a Briton).

The sum of ϕ ers can be defined as that entity y which is such that, given any entity w , w overlaps with y if and only if w overlaps with something that ϕ s. That is:

$$\text{DP4 } \sigma x(\phi x): = \iota y(\forall w(wOy \equiv \exists v(\phi v \wedge wOv)))$$

We can then prove

$$\text{TP3 } y = \sigma x(\phi x) \rightarrow \forall x(\phi x \rightarrow xPy)$$

Empty sums do not exist (they are not a part of reality). Thus if ϕ is a non-satisfied condition, then ' $\sigma x(\phi x)$ ' is undefined. The uniqueness of sums, where they are defined, is guaranteed by **AP1**. We stipulate further that:

$$\text{AP3 } \exists x \phi x \rightarrow \exists y \forall w (w O y \equiv \exists v (\phi v \wedge w O v))$$

which guarantees the existence of sums for satisfied conditions.

From the usual axioms for identity we have $\exists x(x=x)$, from which we can prove a theorem to the effect that the universe exists:

$$\text{TP4 } \exists x \forall y (y P x)$$

Further:

$$\text{TP5 } y P \sigma x(\phi x) \equiv \forall w (w P y \rightarrow \exists v (\phi v \wedge w O v))$$

y is a part of the sum of ϕ ers if and only if all parts of y overlap with some ϕ er.

We have already noted that not all parts of the whole $\sigma x(\phi x)$ need be such as to ϕ . When $y P \sigma x(\phi x)$ if and only if ϕy , then we say that ϕ is a **distributive** condition, and we can prove that $\phi(\sigma x(\phi x))$. Examples of distributive conditions are (for same fixed entity t): *is a part of t*, *is a boundary of t*, and *is an interior part of t*.

We can prove further a theorem to the effect that we can form arbitrary finite unions in the following sense:

$$\text{TP6 } \exists z \forall w (z O w \equiv z O x \vee z O y)$$

We define:

| | |
|--|--------------|
| $1 := \sigma x(x=x)$ | universe |
| $x \cup y := \sigma z(z P x \vee z P y)$ | union |
| $x \cap y := \sigma z(z P x \wedge z P y)$ | intersection |
| $x' := \sigma z(z D x)$ | complement |
| $x - y := \sigma z(z P x \wedge x D y)$ | difference |

Note that all set-theoretical associations of these terms are to be resolutely suppressed. Note, also, that intersections, complements and differences are not always defined. We can, however, prove the following remainder principle:

$$\text{TP7 } x P y \wedge x \neq y \rightarrow \exists z (z = y - x)$$

3. Interior parts

As topological primitive we select the relation *is an interior part of*, which can be elucidated, roughly, as follows. Some entities are what we might call tangential to, i.e. such as to touch or cross the exterior boundaries of, other entities. Some entities are themselves boundaries of other entities, though we note that the boundary of an entity may be outside the entity it bounds (as for example in the case of an open interval in the real line). When x is a part of y that is *off*—which is to say: shares

no parts in common with—the boundary of y , i.e. is neither tangential nor itself a boundary, we say that x is an **interior part** of y and write ' x IP y '. We then stipulate:

- | | |
|---|-----------------------------------|
| AIP1 $xIPy \rightarrow xPy$ | IP is a special sort of P |
| AIP2a $xIPy \wedge yPz \rightarrow xIPz$ | left monotonicity |
| AIP2b $xPy \wedge yIPz \rightarrow xIPz$ | right monotonicity |
| AIP3 $xIPy \wedge xIPz \rightarrow xIP(y \cap z)$ | condition on finite intersections |
| AIP4 $\exists x(\phi x) \wedge \forall x(\phi x \rightarrow xIPy) \rightarrow \sigma x(\phi x)IPy$ | condition on arbitrary unions |
| AIP5 $\exists y(xIPy)$ | |
| AIP6 $xIPy \rightarrow xIP\sigma t(tIPy)$ | |

All of which follow from the usual axioms for a topological space. AIP5 is very strong, and allows us to infer an initially counterintuitive-seeming theorem to the effect that the universe is an interior part of itself:

TIP1 IIP1

The universe is, as we might also say, 'unbounded'. Indeed we can prove that:

TIP2 $\forall x(xIP1)$

Every entity is an interior part of the universe. From AIP4 it follows that IP determines a distributive condition, i.e. that:

TIP3 $tP\sigma x(xIPy) \equiv tIPy$

Hence also we have:

$$tP\sigma x(xIPy) \equiv tIP\sigma x(xIPy)$$

and:

TIP4 $\sigma x(xIPy)IPy$

4. Boundaries

As a first step towards defining what it is for x to be a boundary of y , we define ' xXy ' (x crosses y) by:

$$DP5 \ xXy: = \neg xPy \wedge \neg xDy$$

or, equivalently, for $y \neq 1$,

$$xXy: = xOy \wedge xO(1 - y)$$

i.e., x overlaps both y and its complement. From this it follows trivially that no entity crosses itself and that the universe crosses every entity not identical with the universe itself. We now define ' $xSty$ ' (x straddles y) by:

$$DIP1 \ xSty: = \forall z(xIPz \rightarrow zXy)$$

An entity x straddles an entity y whenever x is such that everything of which it is an interior part crosses y . The definitions then yield immediately that $xSty \rightarrow \neg xIPy$, from which we can prove:

$$\text{TIP5 } xPy \rightarrow xIPy \vee xSty$$

Every part of y is either an interior part of y or such as to straddle y . This follows from AIP1, AIP2a and definitions. As a theorem we also have: $\neg xIPx \rightarrow xStx$.

The entities straddling a given entity can be divided, intuitively, into two classes. On the one hand are those which include among their parts a boundary of the straddled entity. On the other hand there are those—characteristically non-connected—which include no such boundary. We shall refer to the first group as *tangents*. As an example of a non-tangential entity straddling y , consider the sum of two points, both off the boundary of some 3-dimensional solid y , one of which is interior to y , the other exterior. If we examine the case where x is not merely such as to straddle y but is in fact a boundary of y , then we see that what is characteristic of this case is that here x is such that not merely it but also all its parts are such as to straddle the bounded entity. Accordingly we can define **boundary** as follows:

$$\text{DIP2 } xBy := \forall z(zPx \rightarrow zSty)$$

We can now define what it is for x to be a **tangent** of y

$$\text{DIP3 } xTy := \exists z(zPx \wedge zBy)$$

i.e a tangent of y is any entity which has as part a boundary of y . From this definition we can prove that tangents are straddlers, and also that every boundary of y is a tangent of y and is thereby also not an interior part of y . We can prove further, by inspection of the definitions, that:

$$\text{TB1 } xBy \equiv \forall z(zPx \rightarrow zTy)$$

so that, as required, all parts of boundaries of y are not merely straddlers but in fact tangents of y .

4.1. Closure

We can prove further:

$$\text{TB2 } xBy \wedge yBz \rightarrow xBz \quad \text{transitivity}$$

We also have:

$$\text{TB3 } xPy \wedge yBz \rightarrow xBz$$

$$\text{TB4 } xT(y \cup z) \rightarrow xTy \vee xTz \quad \text{splitting}$$

We can prove also the following collection principle for boundaries:

$$\text{TB5 } \forall x(\phi x \rightarrow xBy) \rightarrow \sigma x(\phi x)By$$

5. Topology

These theorems enable us to show that the system so far established defines a topological space in the standard sense, by defining the closure $cl(x)$ of $x \neq 1$ as the union of x with all its boundaries:

$$\text{DIP4 } cl(x) = x \cup \sigma\gamma(yBx)$$

Closure thus defined satisfies the usual Kuratowski axioms:

- I. $xPcl(x)$
- II. $cl(cl(x)) = cl(x)$
- III. $cl(x \cup y) = cl(x) \cup cl(y)$

An entity is called **closed** if and only if it is identical with its closure. $cl(x)$ as defined above can be shown to be identical to the standard topological closure defined equivalently as the union of x with its accumulation points (see below) or as the intersection of all closed entities containing x . A **dense** entity, standardly, is an entity x for which $cl(x) = 1$. The **maximal boundary** of x , defined by:

$$\text{DIP5 } bdy(x) = \sigma\gamma(yBx)$$

now corresponds to the standard topological boundary, defined as the intersection of the closure of an entity with the closure of its complement. Further our *interior*, defined by:

$$\text{DIP6 } int(x) = \sigma\gamma(yIPx)$$

corresponds to the standard topological interior, defined as the difference between an entity and its boundary.

An entity is called **open** if and only if it is identical with its interior. From this we can prove that an entity is open if and only if its complement is closed.

6. Parts and boundaries

The remarks above are non-controversial reformulations of standard topological ideas on a mereological basis. Now, however, we wish to go further and capture mathematically certain ontological intuitions pertaining to ordinary material objects extended in 3-dimensional space and enjoying qualities of, for example, shape and colour. We wish to capture, if one will, the mathematical structures characteristic of the mesoscopic world of everyday perception and action. Three layers of such intuitions can be distinguished:

1. The layer corresponding to general topological notions of boundary, interior, etc., which has been treated above.
2. The layer corresponding to the general properties of 3-dimensional space as we conceive it; this space is 'real' in the sense that it is not an abstract construction; thus it allows no space-filling curves, no objects of fractional dimension, etc.
3. The layer corresponding to the special topological properties of material objects and their associated qualities.

What follows is a provisional attempt to formulate some of the principles underlying 3. It is provisional not least because the definitive statement of such principles must await a more adequate understanding of the general properties of space.

Intuitively, we wish it to be the case that every entity smaller than the universe has a boundary:

$$\mathbf{AB1} \quad y \neq 1 \rightarrow \exists x(xBy)$$

This does not imply that the only *open* entity is **1**. Rather, it tells us that every open entity smaller than the universe is bounded, as it were, on at least one side or in at least one place (consider the case of the Western hemisphere of the universe or of the interstellar vacuum). The boundary itself need then not necessarily be a part of the entity bounded, and indeed that this should be the case in general is ruled out by:

$$\mathbf{TIP6} \quad xBy \wedge yIPz \rightarrow xB(z - y)$$

From this and **TIP2** it follows in particular that every boundary of y is also a boundary of the complement of y . From **TIP6** it follows trivially that:

$$xBx \wedge xIPy \rightarrow xB(y - x)$$

Imagine x is a point in the interior of a 3-dimensional solid y . Then $y - x$ is here the result of deleting this point in such a way as to produce an entity which has a non-constituent boundary in some sense *within its interior*. The opposition between exterior and interior boundaries will receive more detailed attention in what follows.

From **TIP6** and **TIP1** it follows no less trivially that

$$\mathbf{TIP7} \quad xBx \rightarrow xB(1 - x)$$

whence also we can infer that, for any x , $\sigma_y(xBy) = 1$, whence also we can infer that **B** does not define a distributive condition in the first argument.

We can prove further that an entity x is self-bounding (i.e. that xBx) if and only if it has no interior parts:

$$\mathbf{TIP8} \quad xBx \equiv \neg \exists t(tIPx)$$

We can now prove that every boundary which is a part of that which it bounds is also self-bounding:

$$\mathbf{TIP9} \quad xBy \wedge xPy \rightarrow xBx$$

This does not imply, however, that we are defending a position which stands in conflict with the commonsensical intuition to the effect that that which bounds, for example, a surface is the *outer form* or *edge* of the surface. That the surface is self-bounding is consistent with its having as boundary in addition some proper part of itself, including its outer form.

From **AB1** and **TIP8** we could then prove that boundaries have no interior parts. From **TB5** we can prove:

$$\mathbf{TIP10} \quad xBz \wedge yBz \rightarrow (x \cup y)Bz$$

And we have also:

$$\mathbf{TIP11} \quad xPy \rightarrow xBy \vee xIPy \vee \exists uv(uBy \wedge vIPy \wedge u \cup v = x)$$

Every part is either a boundary or an interior part or the union of a boundary and an interior part (where the disjunctions are of course exclusive).

7. Dependent existence and Brentano's thesis

We wish now to capture the commonsensical intuition to the effect that boundaries exist only as boundaries, i.e. that boundaries are dependent particulars: entities which are such that, as a matter of necessity, they do not exist independently of the entities they bound ([6], Part One; [10,65]). This thesis—which stands opposed to the set-theoretic conception of boundaries as, effectively, sets of points, each one of which can exist though all around it be annihilated—has a number of possible interpretations. One general statement of the thesis would assert that the existence of any boundary is such as to imply the existence of some entity of higher dimension which it bounds. Here, though, we may content ourselves with a simpler thesis, one whose formulation does not rest on the tricky notion of dimension, to the effect that every boundary is such that we can find an entity which it bounds of which it is a part and which is such as to have interior parts. (Note that analogous theses could be formulated with respect to other neglected or metaphysically contested categories of entities: for example holes, shadows, colours, universal forms, thoughts, minds, etc.) Define first of all the predicate *is a boundary* by means of:

$$\text{DIP7 } \text{Bd}(x) := \exists y(xBy)$$

We can then write:

$$\text{AB2 } \text{Bd}(x) \rightarrow \exists zt(xBz \wedge xPz \wedge tIPz) \quad \text{First Brentanian Thesis}$$

From this the theorem to the effect that all boundaries are self-bounding can be inferred immediately via **TIP9**. **AB2** is not very strong, however. For it seems that we have:

$$xB_y \rightarrow xB(y \cup t)$$

for any arbitrary t that is separate from the closure of y . Thus **AB2** is satisfied by choosing t such that $tIPt$ and setting z equal to the scattered object $x \cup t$.

A Brentanian thesis of the required strength must impose on z in **AB2** at least the additional requirement of connectedness. To this end, we define, for $x \neq 1$ and $y \neq 1$:

$$\text{DCn1 } xSy := \text{cl}(x)Dy \wedge xD\text{cl}(y)$$

We then say that $1 - (x \cup y)$ separates x from y . Thus $\text{bdy}(x)$ separates $\text{int}(x)$ from $\text{int}(1 - x)$ in the given sense. We can then prove:

$$\text{TS1 } xSy \wedge wPx \wedge vPy \rightarrow wSv$$

Further we know that disjoint entities are separate if either both are open or both are closed.

Define **connected**:

$$\text{DCn2 } \text{Cn}(x) := x \neq 1 \wedge \neg \exists yz(ySz \wedge x = y \cup z)$$

We then have a new Brentanian thesis affirming, for connected boundaries, the existence of connected wholes which they are the boundaries of:

$$\text{AB3 } \text{Bd}(x) \wedge \text{Cn}(x) \rightarrow \exists zt(xPz \wedge xBz \wedge \text{Cn}(z) \wedge tIPz) \quad \text{Second Brentanian Thesis}$$

Note that **DIP2** yields no guarantee that boundaries are connected in the sense here defined.

8. Exterior and interior boundaries

Intuitively, boundaries can be divided into exterior and interior (See [6], Part One, I; [65]). The exterior boundaries of x are, as it were, boundaries which separate x from the remainder of the universe. Exterior boundaries in this sense may or may not be parts of the things (or other entities) they bound, and they may or may not be on the exterior of the relevant entity in the normal understanding of this phrase. Thus they may be the boundaries of holes, including internal cavities; see, on the wealth of possibilities in this respect, [9]. We can distinguish also, however, **interior boundaries**—the boundaries which would result, intuitively, if interior parts of x were exposed to the light of day by annihilation of what stands between them and x 's exterior. Interior boundaries are in this sense potential exterior boundaries; they are those parts of x which are boundaries of interior parts of x but not themselves, or not yet, boundaries of x . We define:

$$\text{DIB1 } x\text{IBy} := x\text{IPy} \wedge x\text{Bx}$$

We might consider also in this connection the idea of a slicing principle to the effect that, in those cases where $x\text{By}$ results from the fact that x is a deleted region inside some $z = y - x$, we can slice z along x to produce one or more entities of which x is both exterior boundary and part.

8.1. Points

We can prove:

$$\text{TPt1 } \forall y(y\text{Bx} \equiv x = y) \rightarrow \text{Pt}(x)$$

A point is that which has no parts other than itself (**DP3**). We can now stipulate that a point has no boundaries other than itself (a condition which might also have been used as a definition of 'point'):

$$\text{APt1 } \text{Pt}(x) \rightarrow \forall y(y\text{Bx} \equiv x = y)$$

This is equivalent to the proposition:

$$\text{Pt}(x) \rightarrow x = \text{cl}(x)$$

which is one (mereological) formulation of the usual condition on a T1 topological space. A more standard formulation would be:

$$\neg \forall x \forall y (x \neq y \wedge \text{Pt}(x) \wedge \text{Pt}(y) \rightarrow \exists z ((x\text{IPz} \wedge \neg y\text{IPz}) \vee (y\text{IPz} \wedge \neg x\text{IPz})))$$

From **APt1** it follows further that:

$$\text{TPt2 } \text{Pt}(x) \wedge x\text{By} \wedge x \neq y \rightarrow \neg \text{Pt}(y)$$

and, by setting $y = \mathbf{1} - x$:

$$\text{TPt3 } \text{Pt}(x) \rightarrow \exists y (x \neq y \wedge x\text{By})$$

This goes some way towards capturing the anti-set-theoretical intuition to the effect that there are, in reality, no isolated points.

A **neighbourhood** of a point x is any entity y of which x is an interior part. A punctured

neighbourhood of x is a neighbourhood with x deleted. An **accumulation point** may now be defined as follows:

$$\mathbf{DA1} \ xAy: = Pt(x) \wedge \forall z(xIPz \wedge x \neq z \rightarrow (z - x)Oy)$$

i.e., an accumulation point of y is any point x which is such that any punctured neighbourhood of x overlaps y . We now prove:

$$y \text{ is closed} \rightarrow \sigma x(xAy)Py$$

From the definitions we can prove

$$\mathbf{TPt4} \ xAy \rightarrow xBy \vee xIPy$$

By **TIP11** we can prove generally that: $Pt(x) \wedge xPy \rightarrow xBy \vee xIPy$.

$$\mathbf{TPt5} \ xBy \wedge xDy \wedge Pt(x). \rightarrow xAy$$

We may now go on to define interior points and boundary points as follows:

$$\mathbf{DPt1} \ xIPty: = Pt(x) \wedge xIPy$$

$$\mathbf{DPt2} \ xBPty: = Pt(x) \wedge xBy$$

Using axiom **AIP3** we can prove further that interior points are accumulation points.

$$\mathbf{TPt6} \ xIPty \rightarrow xAy$$

Exploiting an analogy with Brentano's notion of the 'full plerosis of an internal boundary' ([6], Part One, I) we may define further:

$$\mathbf{DA2} \ xFAy: = Pt(x) \wedge \forall z(xBz \wedge x \neq z \rightarrow \exists t(tIPy \wedge tPz \wedge xAt))$$

x is a **full accumulation point** for y if and only if it is an accumulation point to y in all the directions in which x can serve as boundary (x is, as it were, the centre of a spherical ball within y).

$$\mathbf{TPt7} \ xFAy \rightarrow xAy$$

9. Things

Return, once again, to the Second Brentanian Thesis:

$$\mathbf{AB3} \ Bd(x) \wedge Cn(x) \rightarrow \exists zt(xPz \wedge xBz \wedge Cn(z) \wedge tIPz)$$

This is still too weak if we wish to capture the intuition to the effect that exterior boundaries in the real material world are boundaries of *things*, for we require at least a further requirement to the effect that the entity z in question is the object bounded and not its complement. By **TIP6** each boundary behaves symmetrically in relation to the object and its complement. From the perspective of common sense, however, the boundary of, say, this stone is much more intrinsically connected to the stone than it is to the rest of the universe. To capture this notion formally would require (what we do not yet have) an adequate formal account of things, which we can characterize briefly as 3-dimensional material entities which are at the same time maximally connected. Thus my arm is 3-dimensional and

material but it is not a thing, and similarly the scattered whole consisting of my arm and this pen is 3-dimensional and material but it, too, is not a thing [65]. To this end we shall define the notion of a 'component' or *maximally connected entity*. For values of x such that $Cn(x)$ we set:

$$DCn3 \text{ cm}(x) := \sigma y(xPy \wedge Cn(y))$$

The component of x is the maximal connected entity containing x . We can then prove:

$$TCn1 \ z = \text{cm}(x) \rightarrow \forall y(Cn(y) \wedge zPy \rightarrow y = z)$$

Components are, if one will, those natural units from out of which the world is built. Such natural units can be found not only in the realm of 3-dimensional material things, but also, for example, in the temporal dimension (salutes, weddings, lives, are natural units in the realm of events and processes). To deal with these matters, here, however, as also with the concepts of dimension (edge, surface) and with the relations between units and their underlying stuffs, all of this would lead us too far afield.

10. From cognitive linguistics to ontology

Concepts and theories derived from mereology and topology have been utilized already in a variety of ways not only in the field of ontological engineering but also in a range of other cognitive sciences. Examples of such work include:

- Analyses of natural language, especially of object-categorization, verb-aspect and the mass-count distinction: [9,15,32,34,46,47,57,58].
- Work in the theory of geographic information systems: [21,22,37,43].
- Investigations of spatial perception, and of the spatial properties of mental representations; studies in image-processing, for example in automatic analysis of X-ray images for medical and other purposes: [9,23,59,66,77].
- Contributions to qualitative or 'naive' physics and to the field of common-sense reasoning: [20,35,36,56,59,61,65,68,76].

It is, however, in work in the area of cognitive linguistics on the part of Lakoff, Talmy, Langacker, Jackendoff and others that topological notions have been most explicitly and systematically applied. (See especially [71]ff; [7,40,41], and the related work [52]ff, and [79]f.) The importance of topology to the conceptual structuring effected by language is illustrated most easily in the case of prepositions. As Talmy notes, a preposition such as 'in' is magnitude neutral (in a thimble, in a volcano), shape neutral (in a well, in a trench), closure neutral (in a bowl, in a ball); but it is also discontinuity neutral (in a bell-jar, in a bird cage). The task of formally defining the precise nature of the transformation which maps one in-structure onto another under these conditions and in such a way as to do justice to the features illuminated by Talmy's many examples, is a difficult one; in the absence of appropriate formal theories of the mereotopological sort, however, the work of the cognitive linguists will remain subject to the charge that it has not gone beyond the stage of narrative evidence-gathering. As Wildgen points out in criticizing Talmy: 'The quasi-formal symbols in Talmy's descriptions come from algebra, geometry, topology and vector-calculus, but the mathematical properties of these concepts are neither exploited nor respected' [80], p. 32. Similar criticisms could be marshalled against Lakoff and his associates also, and it is perhaps above all in helping to meet such criticisms that the mereotopological approach can be of most immediate benefit to progress in cognitive science.

11. Coda: From cognitive linguistics to general ontology

Cognitive linguistics seeks to provide an account of the ways in which we impose conceptualizations or categorizations or structurings on reality through our uses of natural language. The formal resources of mereotopology can be used, finally, to generalize this project to one of providing an account of conceptualizations and categorizations in general, i.e. not merely those imposed via uses of language but also those generated by other cognitive modes of access to reality, including perception, scientific theories, the map-making activities of the geographer, knowledge-sharing systems, and so on—to move, in other words, from cognitive linguistics to general ontology. Such partition-systems may be applied on different levels (thus atoms, molecules, cells, organisms, populations can all be conceived as products of partition in the sense here at issue). In addition, partition-systems may involve boundaries of different sorts: for example, boundaries of different dimensions, boundaries which are more or less determinate, boundaries which are more or less enduring, connected and non-connected boundaries, interior and exterior boundaries, and so on.

Perhaps the most important typological division amongst boundaries from our present point of view, however, is that between (1) natural or autonomous boundaries—those which reflect genuine divisions or heterogeneities in reality, and which thus exist independently of all conceptualizing or categorizing activity on our part: for example the boundaries around my body, heart, lungs, cells, and so on; and (2) boundaries which correspond to no genuine local heterogeneity (natural divisions) on the side of the bounded entities themselves: for example the boundaries between the Northern and Southern hemispheres, between one calendar month and the next, and so on.

Let us call boundaries of the first sort genuine or *bona fide* boundaries, boundaries of the second sort *fiat* boundaries, a terminology that is designed to draw attention to the sense in which the latter owe their existence to acts of human decision or fiat or to cognitive processes of similar sorts [67]. Complete boundaries within a partition yield *objects*: countries on the globe, months on the calendar. Such objects, too, may be either *bona fide* or fiat objects in our suggested terminology. Examples of genuine objects are: you and me, the planet earth. Examples of fiat objects are: all geographical entities demarcated in ways which do not track qualitative differentiations or physical discontinuities in the underlying territory. Clearly geographical fiat objects will in general have boundaries which involve a combination of *bona fide* and fiat elements, for such objects will in most cases owe their existence not merely to human fiat but also to associated real properties of the relevant factual material.

Some ontologists, and most cognitive linguists, have, now, embraced a thesis to the effect that everything is a fiat object, that there are no partition-independent realities to which our humanly constructed partitions or conceptualizations would correspond. According to this view, which we might call linguistic idealism, the reality which exists independently of our experiences is unknowable as such. That to which we are related when we use language correctly is, on this linguistic version of standard Kantian metaphysics, a *shaped and contoured reality*, never the amorphous and unknowable matter of reality (in) itself. Two versions of linguistic idealism can be distinguished: a global thesis, to the effect that, in the terminology introduced above, all objects (or all cognitively relevant objects) are fiat objects; and a local thesis to the effect that fiat-object-status is to be assigned to objects in specific and limited areas—for example in the area of conventional units of measure.

Now there are a number of reasons why the general thesis of linguistic idealism must be rejected: how would the thesis that all objects are fiat objects be applied to the conceptualizers themselves, the

demarcating subjects who construct the relevant systems of fiat boundaries? And how would fiat demarcation be possible if there were no genuine landmarks which we (or the first fiat demarcators) were able to discover, and in relation to which fiat demarcation becomes possible and objectively communicable? How would cumulative fiat demarcations be possible unless prior fiat demarcations had become allied, to some degree, with real perceptible differences in relation to which later fiat demarcations could be drawn? In fact, as in geography so in relation to the demarcations we impose upon reality through language and in other ways, we have typically to deal with partitions which involve a mixture of fiat and *bona fide* demarcations. If I say 'blood flowed from his nose' or 'he was bleeding from the nose' then I am capturing a genuine event, genuinely distinct from other events (of the postman ringing the doorbell, the cat barking), but I am capturing this event via two distinct articulations, one or both of which must involve some fiat component. As Husserl already stressed in his *Logical Investigations*, only certain determinate parts of our expressions can have something corresponding to them in sensibly perceivable reality. 'When we consider the various simple judgment forms: *A is P*, *An S is P*, *The S is P*, *All S are P*, and so on, it is easy to see that only at the places indicated by letter-symbols ... can meanings stand that are fulfilled in perception itself' ([39], 779). As Husserl also points out, and his remarks here can be applied to the general topic of the nature of conceptualizations and categorizations of reality, 'each given object can be grasped in explicating fashion': in acts of articulation we put its parts 'into relief', in relational acts we bring the relieved parts into relation, whether to one another or to the whole. And only through these new modes of conception do the connected and related members gain the character of 'parts' or of 'wholes' ([39], 792).

The world, from the realist, Husserlian perspective we are defending, has accordingly a certain sensible, material stuff. Within this stuff we can pick out via our use of language and by other means many different sorts of objects by drawing fiat boundaries within the realm of matter. By means of suitable acts of relating or of setting into relief we can make for ourselves a range of different sorts of formally determined structures and we can carve out for ourselves new objects in cumulation by cleaving the relevant matters along formally determined contour lines. This drawing of fiat boundaries is a purely intellectual affair. But the objects it picks out are not denizens of any separate, purely intellectual realm. It is, rather, as if these objects are added as political boundaries come to be added—or delineated within—areas of virgin territory, i.e. in such a way as to leave all sensible, material structures and all real unities at least initially unaffected.

Ontological conceptualizations or categorizations can now be defined quite generally as systems of complete boundaries which partition a given domain into objects or regions or elements of different sorts. More generally, they are systems of boundaries which generate, from a given whole as starting point, another whole with more or fewer or different parts. The framework of mereotopology is surely not sufficient to provide a coherent formal expression for all distinctions which are of importance for the general theory of conceptualizations and categorizations. For the purposes of the cognitive scientist and of the ontological engineer, however, it can provide a uniquely fertile starting-point.

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